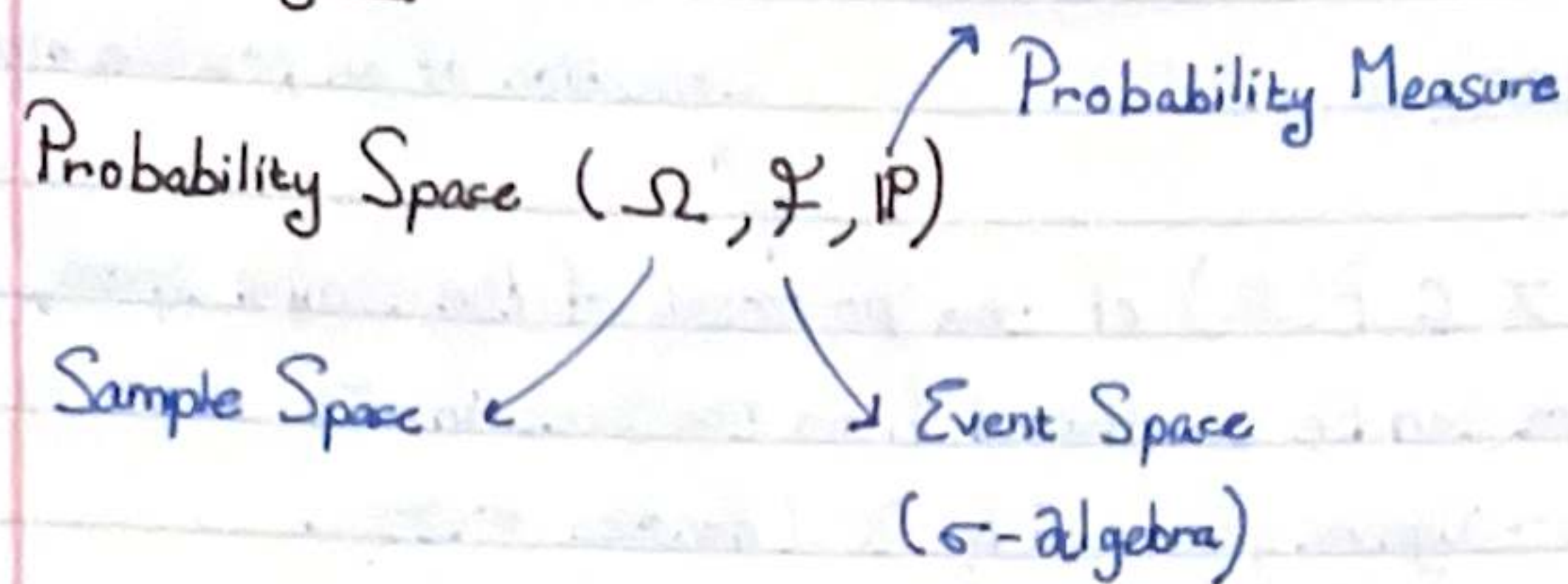


Probability.



- The Sample Space Ω is the set of all possible outcomes of an experiment ($\Omega \neq \emptyset$)
e.g. $\{H, T\}, \{1, 2, 3, 4, 5, 6\}$

Tossing a coin
Once.

Rolling a dice once.

- The event Space is the set / grouping of outcomes according to a ^{chosen} definition of an event.
e.g. Rolling even no. : $\{2, 4, 6\}$
Flipping Heads : $\{H\}$

The event Space is structured as a σ -algebra for probability calculus to behave as intended.

The grouping of the event Space $\mathcal{E} \subseteq \mathcal{P}(\Omega)$ is a subset of the power set of Ω .

$\mathcal{F}$ must satisfy both the specified events and the σ -algebra conditions.

Properties:

- $\Omega \in \mathcal{F}$
- $A \in \mathcal{F} \Rightarrow (\Omega \setminus A) \in \mathcal{F}$
- From 1 & 2, $\emptyset \in \mathcal{F}$

$$4) \text{ for } A_1, A_2, A_3, \dots \in \mathcal{F} \Rightarrow \bigcup_{i=1}^{\infty} A_i \in \mathcal{F}$$

Closed under countable union

examples of σ -algebras include

- $\mathcal{F}_1 = \{\emptyset, \Omega\}$
- $\mathcal{F}_2 = \mathcal{P}(\Omega)$
- $\mathcal{F}_3 = \{\emptyset, A, A^c, \Omega\}$

$$5) \text{ From 2 \& 4, } \bigcup_{i=1}^{\infty} A_i^c \in \mathcal{F} \Rightarrow \left(\bigcup_{i=1}^{\infty} A_i^c \right)^c \in \mathcal{F}$$

De Morgan's Laws

$$\Rightarrow \bigcap_{i=1}^{\infty} A_i \in \mathcal{F}$$

$\mathcal{F}$ is also closed under countable intersection

Generated σ -algebras

Collection of all possible events.

For any subset $\mathcal{T} \subseteq \mathcal{P}(\Omega)$ of the powerset of the sample space, a unique minimal σ -algebra can be constructed from the sets in $\mathcal{T}$. It is called the σ -algebra generated by $\mathcal{T}$ (denoted $\sigma(\mathcal{T})$).

↳ This is done by taking an arbitrary subset of $\mathcal{P}(\Omega)$ e.g. ~~$\{\{1,2\}, \{3,4,5,6\}\}$~~ and applying the σ -algebra axioms to it.

e.g. $\{\{1,2\}\}$

Step ① Add the complement of the set in $\mathcal{T}$
 $\{1,2\}^c \rightarrow \{3,4,5,6\}$

~~② Add Ω~~

Step ② $\Omega = \{1,2\} \cup \{3,4,5,6\}$

Step ③ $\Omega^c = \emptyset$ or $\{1,2\} \cap \{3,4,5,6\} = \emptyset$

$\mathcal{T} = \{\emptyset, \{1,2\}, \{3,4,5,6\}, \Omega\}$ is the smallest σ -algebra containing $\{1,2\}$.

e.g. $\begin{matrix} A & B & C \\ \{1,2\} & \{3,4\} & \{5,6\} \end{matrix}$

→ A σ -algebra can be formed by any partition of Ω

$A \cup B \cup C \in \mathcal{T} = \Omega$
 $A \cap B \cap C \in \mathcal{T} = \emptyset$ (or $\Omega^c = \emptyset$)
 $A \cup B, A \cup C, B \cup C \in \mathcal{T}$
 $(A \cup B)^c, (A \cup C)^c, (B \cup C)^c \in \mathcal{T}$
 partitions.
 combinations of the union of the partitions.

↳ Method of generating another smallest σ -algebra

σ -algebras generated by ~~countable partitions~~

Grouping of elements such that every element

Borel σ -algebra (over $\mathbb{R}^n$)

A little bit of Topology.

A topology on set X is a collection of $\mathcal{T}$ of subsets of X
 $\mathcal{T} \subseteq \mathcal{P}(X)$

S.t the following axioms are satisfied:

1) $\emptyset \in \mathcal{T}, X \in \mathcal{T}$

2) Closed under arbitrary union

If $\{U_i\}_{i \in I}$ is any collection of sets in $\mathcal{T}$ then their union is also in $\mathcal{T}$:

$$\bigcup_{i \in I} U_i \in \mathcal{T}$$

3) Closed under finite intersection

If $U_1, U_2, U_3, \dots, U_n \in \mathcal{T} \Rightarrow U_1 \cap U_2 \cap U_3 \cap \dots \cap U_n \in \mathcal{T}$

$(X, \mathcal{T})$ where $\mathcal{T}$ is a topology on X is called a topological space
 Sets in $\mathcal{T}$ are called open sets.

Open Sets

Metric Space defn

for $U \subseteq (X, d)$ a set is open if for every point $x \in U, \exists r > 0$ s.t the open ball $B(x, r) \subseteq U$.

$B(x, r) = \{y \in X \mid d(x, y) < r\} \rightarrow$ Every point in U has a neighbourhood contained in U .

$(0, 1)$ is open because for any point $x \in (0, 1)$ we can find a small interval around x that stays entirely within $(0, 1)$. → Relates on defn of limits & infinitely small...

$[0, 1]$ is not open because the end points 0, 1 do not have neighbourhoods that stay within the set.

~~Topology~~

Examples of Topologies

(a) Standard topology on $\mathbb{R}$.

$$X = \mathbb{R}$$

$\mathcal{T}$ is the collection of all open intervals (a, b) and the union of such intervals.

(b) Discrete Topology

$$X = \{a, b, c\}$$

$$\mathcal{T} = \mathcal{P}(X)$$

Note the Striving similarity Topologies bear to σ -algebras.
(although missing complementarity)

~~No~~ σ -algebras are sets

(c) Trivial Topology

$$X = \{a, b, c\}$$

$$\mathcal{T} = \{\emptyset, X\}$$

Borel Sets and Borel σ -algebras.

Borel Set: They are NOT a subset of a topology.

A topology on set X is a collection of sets that satisfy the conditions for open sets.

A borel set is any set that can be formed from the open sets of a topological space through a combination of the following operations:

- Countable union
- Countable intersection
- Complementation

~~A borel set is like a σ -algebra but lacking the requirement for $\emptyset$ & X .~~

~~Is this true?~~

All open sets are borel sets but not all borel sets are open sets.

Borel

Lebesgue

A collection of Borel Sets make up the Borel σ -algebra.

The Borel σ -algebra is the smallest σ -algebra containing $\mathcal{T}$

$$\mathcal{B}(X) \supset \mathcal{B}(\mathcal{T}) \rightarrow \mathcal{B} = \sigma(\text{Open sets in } \mathbb{R})$$

$\mathcal{B}$, The Borel σ -algebra is the smallest σ -algebra generated by the collection of open intervals/open sets in $\mathcal{T}$.

Borel Measure

A borel measure μ defined on the Borel σ -algebra $\mathcal{B}(X)$ of a topological space X assigns size to the subset sets in the Borel σ -algebra.

~~Note: The Borel sets are a subset of a topological space. The collection of these subsets form a σ -algebra. The σ -algebra is a subset of the powerset of the topology on X .~~ $\rightarrow$ FALSE

The borel measure satisfy the following properties:

① $\mu: \mathcal{B}(X) \rightarrow \mathbb{R}$ (The domain of the measure is defined on $\mathcal{B}(X)$).

② $\forall A \in \mathcal{B}(X), \mu(A) \geq 0$ (Non-negative measure)

③ $\mu(\emptyset) = 0$

④ σ -Additivity/Countable additivity.

$\{A_n\}_{n=1}^{\infty}$ is a sequence of disjoint Borel sets,

$$\text{then } \mu\left(\bigcup_{n=1}^{\infty} A_n\right) = \sum_{n=1}^{\infty} \mu(A_n)$$

(disjoint only)

$$X: (\Omega, \mathcal{F}, P) \rightarrow (\mathbb{R}, \gamma)$$

$$\Omega \rightarrow \mathbb{R}$$

Real line

distribution

of outcomes

Borel measure

X maps outcomes of Ω to topological space $\mathbb{R}$.

Now, that topological space forms a Borel set $\mathcal{B}(\mathbb{R})$

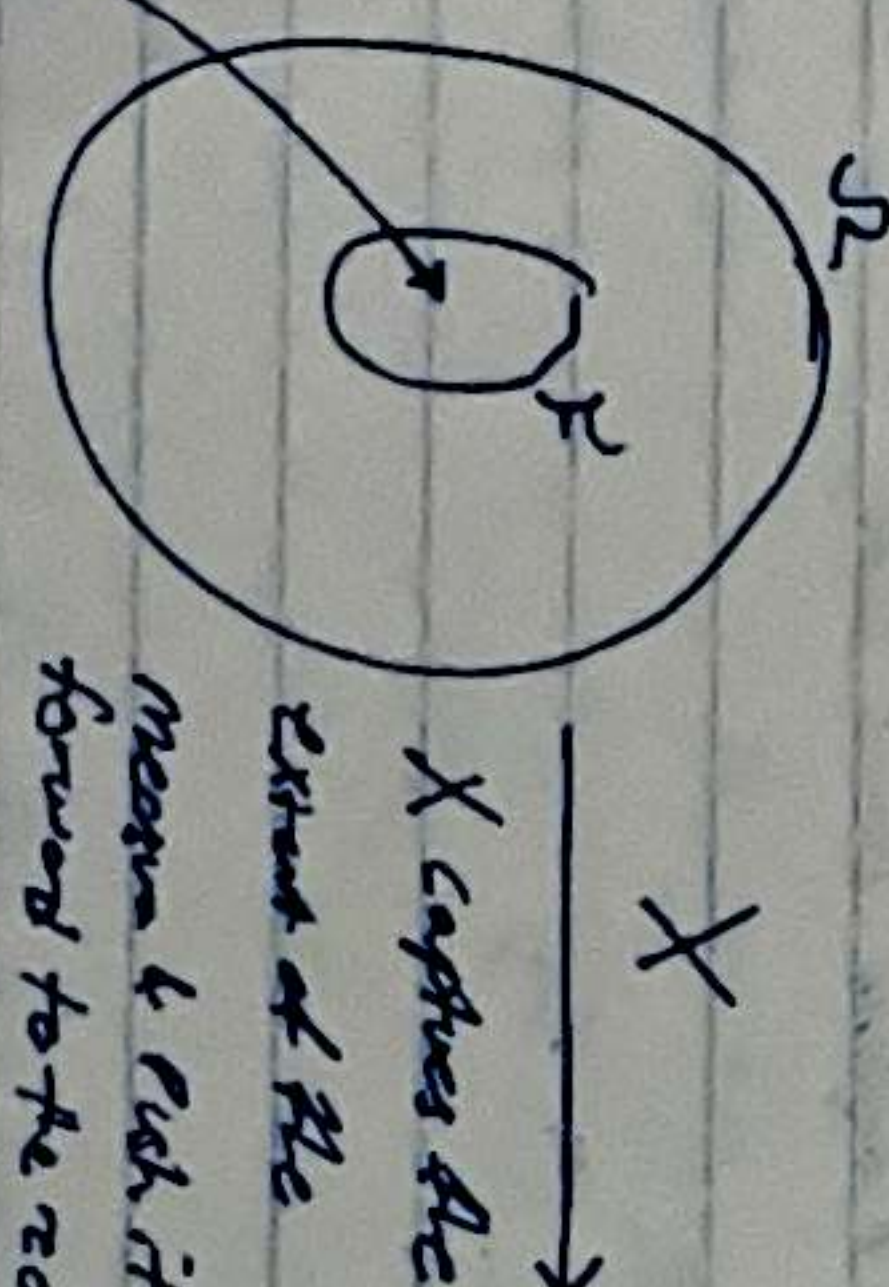
$$P: \mathcal{F} \rightarrow \mathbb{R}$$

Now P maps $\mathcal{F}$ onto $\mathbb{R}$

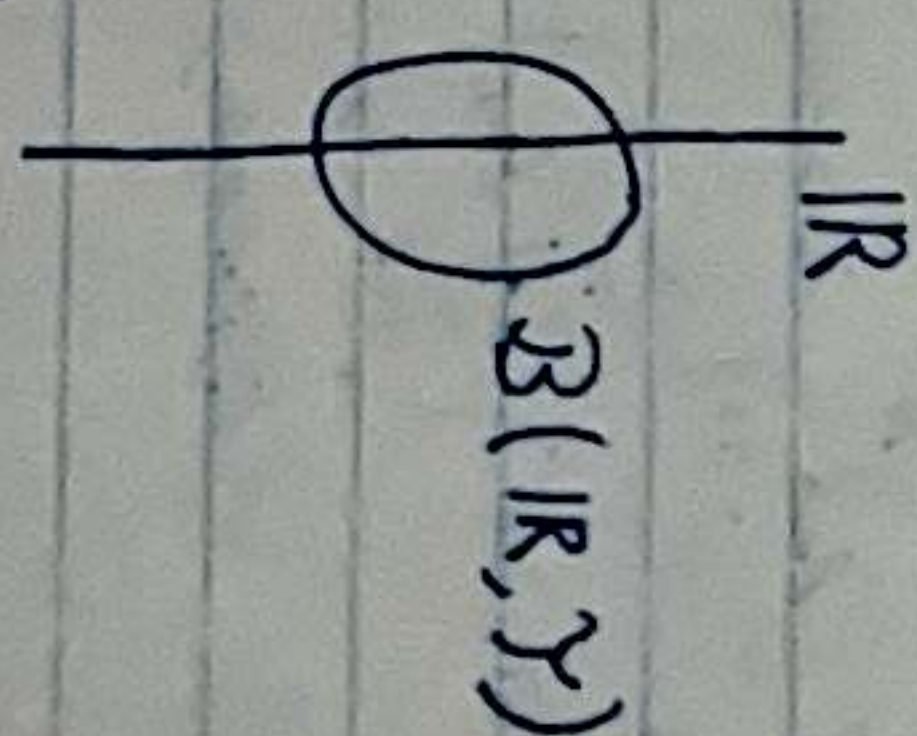
$\mathcal{F}$ is thus defined on $\mathcal{B}(\mathbb{R})$ too.

This is how events in $\mathcal{F}$ are lined to the real line through random variables.

Measures size of sets



X captures the extent of the event of the measure & push it forward to the real line



This set is captured by a ~~measure~~ probability distribution function.

P measures the extent an outcome ω lies in $\mathcal{F}$ relative to Ω

X interprets the "extent" in a meaningful $\mathbb{R}$ and and quantifiable way on a real line.

Probability Measure

$$(\Omega, \mathcal{F}, P)$$

$$P: \mathcal{F} \rightarrow \mathbb{R} [0, 1]$$

- It is a measure defined from the event space σ -algebra to the interval $[0, 1]$.
- It is a special case of a borel measure, being normalized to $P(X) = 1$
- P is defined on the σ -algebra of events while μ (borel) is defined on borel σ -algebras.
- P is used to assign probabilities to events.

Desirable Properties of P .

$$1) \mathcal{F} \subseteq \mathcal{P}(\Omega)$$

$$2) P: \mathcal{F} \rightarrow [0, 1]$$

$$\text{S.t.: } P(\Omega) = 1$$

$$P \text{ is } \sigma\text{-additive} \rightarrow P\left(\bigcup_{i=1}^{\infty} A_i\right) = \sum_{i=1}^{\infty} P(A_i)$$

Calculation Properties

$$P\left(\bigcup_{i=1}^n A_i\right) = \sum_{i=1}^n P(A_i)$$

↳ The ^{measure} probability of a finite union is the sum of their individual probabilities.

$$P(A^c) = 1 - P(A)$$

$$P(A \cup A^c) = P(A) + P(A^c)$$

$$P(\Omega) = 1 = P(A) + P(A^c)$$

$$\Rightarrow P(A^c) = 1 - P(A)$$

$$P(\emptyset) = 0$$

$$P(\emptyset) = 1 - P(\Omega)$$

For $A, B \in \mathcal{F}$

$$A \subseteq B \Rightarrow P(A) \leq P(B)$$

$A \cap B \in \mathcal{F}$

$$B \setminus A = B \text{ only}$$

$$B = A \cup B \setminus A$$

$$P(B) = P(A) + P(B \setminus A)$$

≥ 0

For any A or B ,

B will always be greater than A

$$\Rightarrow P(A) \leq P(B)$$

$$P(A \cup B) = P(A) + P(B) - P(A \cap B)$$

$$P\left(\bigcup_{i=1}^{\infty} A_i\right) \leq \sum_{i=1}^{\infty} P(A_i)$$

Non-disjoint Union in these cases.

Probability Measures help assign weights to the elements (event set collection) of a σ -algebra so as to characterize likelihood of events.

Examples

$$\Omega = \{1, 2\}$$

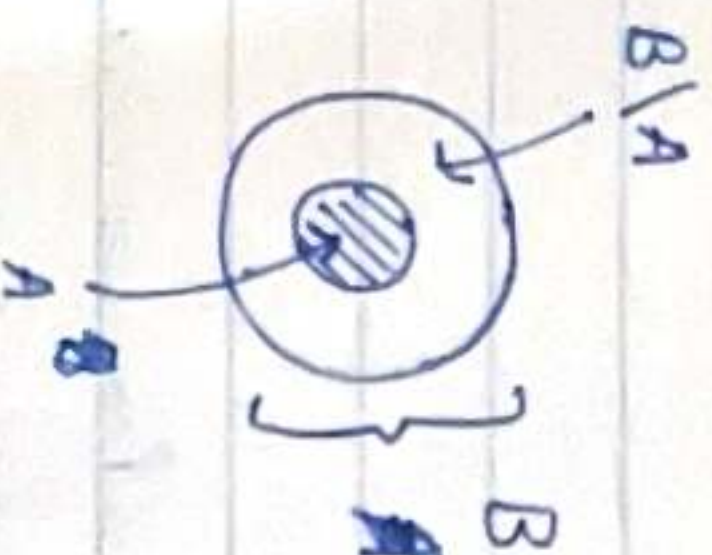
Define $P: \mathcal{F} \rightarrow [0, 1]$ $\begin{cases} P(B) = 0 \\ P(A) = 1 \end{cases}$
 $\hookrightarrow P$ must always satisfy the two conditions as well as the post properties.

$$\mathcal{F}_0 = \{\emptyset, \Omega\} \quad \mathcal{F}_1 = \mathcal{P}(\Omega) = \{\{\emptyset\}, \{\Omega\}, \{1\}, \{2\}, \{1, 2\}\}$$

P is a probability measure on $\mathcal{F}_0$ as $P(\emptyset) = 0, P(\Omega) = 1$

but not on $\mathcal{F}_1$ as $P(\{1 \cup 2\}) = P(\{1\}) + P(\{2\}) = 2$

$$P(\Omega) = 1$$



Naïve definition of Probability

Let $\mathcal{F} = \mathcal{P}(\Omega)$

$$\forall A \in \Omega \quad P(A) \stackrel{\text{def}}{=} \frac{|A|}{|\Omega|} \quad \left(\begin{array}{l} \text{Size} \\ \text{Number of events divided by total outcomes} \end{array} \right)$$

P is a probability measure on $\mathcal{F}$.

$$P(\Omega) = \frac{|\Omega|}{|\Omega|} = 1$$

P is σ -additive (finite additive)

$$P\left(\bigcup_{i=1}^n A_i\right) = \frac{1}{|\Omega|} \left| \bigcup_{i=1}^n A_i \right| = \frac{1}{|\Omega|} \sum_{i=1}^n |A_i| = \sum_{i=1}^n P(A_i)$$

Dirac Measure

Let $\mathcal{F}$ be a σ -algebra

Categorise whether a is in the

Let $x \in \Omega$

$$P_x(A) = \begin{cases} 1, & x \in A \\ 0, & x \notin A \end{cases}$$

is a probability measure $\delta_x(A)$



Dirac Measure (Point Set)

$$\mathcal{F} = \mathcal{P}(\Omega) \text{ possible}$$

$$P: \Omega \rightarrow [0, 1] \text{ s.t. } \sum_{x \in \Omega} P(x) = 1$$

$$P(A) \stackrel{\text{def}}{=} \sum_{x \in A} P(x) \text{ for all } A \subseteq \Omega$$

Probability measure on power set

entire sample space (or power set of all other possible events)

Example

Event space being all possible combinations of events

$$\Omega = \{1, 2, 3\} \quad \mathcal{F} = \mathcal{P}(\Omega)$$

$$p(2) = 0.2$$

$$p: \Omega \rightarrow [0, 1] : p(1) = 0.4, p(2) = 0.4, p(3) = 0.2$$

Probability measure assesses likelihood of outcomes

$$\sum_{x \in \Omega} p(x) = p(1) + p(2) + p(3) = 1$$

$$IP(A) = \sum_{x \in A} p(x) \quad \text{for all } A \subseteq \Omega$$

$$IP(\{1, 2\}) = p(1) + p(2) = 0.8$$

Event Space groups outcomes as desired

σ -algebra ensures that combining individual outcome probability to give event probability follows rule of probability.

Probability Measure over an uncountable set.

$$\Omega = [0, 1]$$

$$\mathcal{F} = \mathcal{B}([0, 1])$$

Random

Number between 0 and 1

is chosen at random, uniformly.

$$\lambda([a, b]) = b - a \quad [a, b] \subseteq [0, 1]$$

Interpretation of that

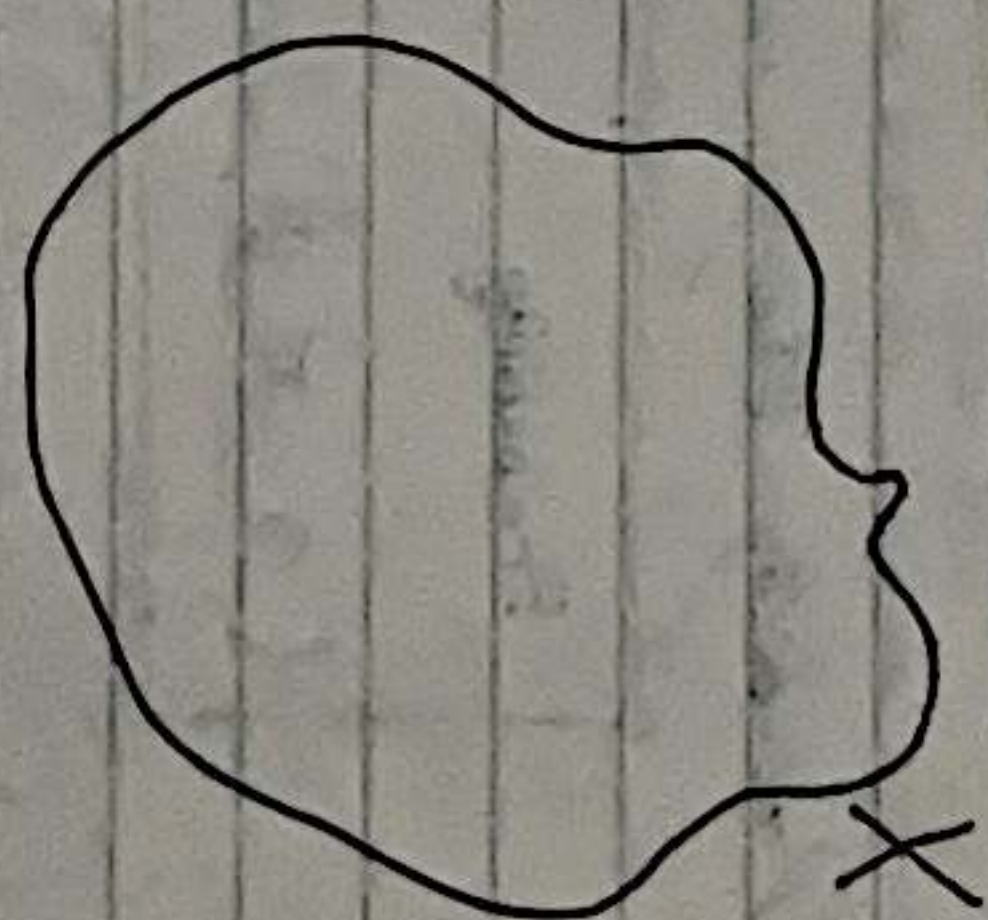
$$\lambda(\Omega) = \lambda([0, 1]) = 1$$

$$([0, 1], \mathcal{B}([0, 1]), \lambda)$$

Random Variable

Large Picture.

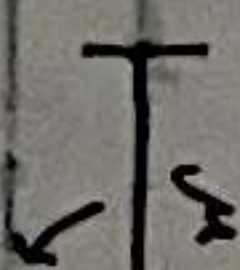
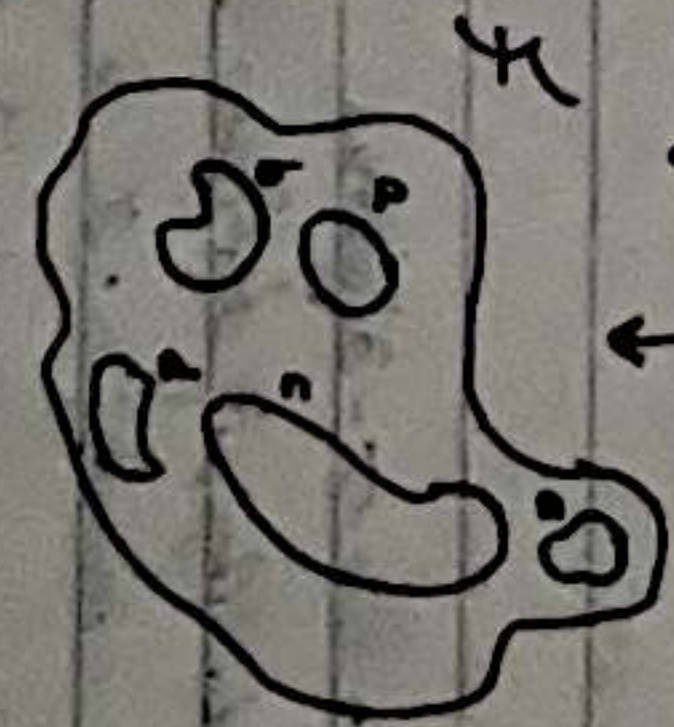
We have a set of events



Ensuring measure occurs properly

σ -algebra

Contains $\emptyset$ & Ω
 $\mathcal{F} \subseteq \mathcal{P}(\Omega)$



Assigns Size to each of these subsets.

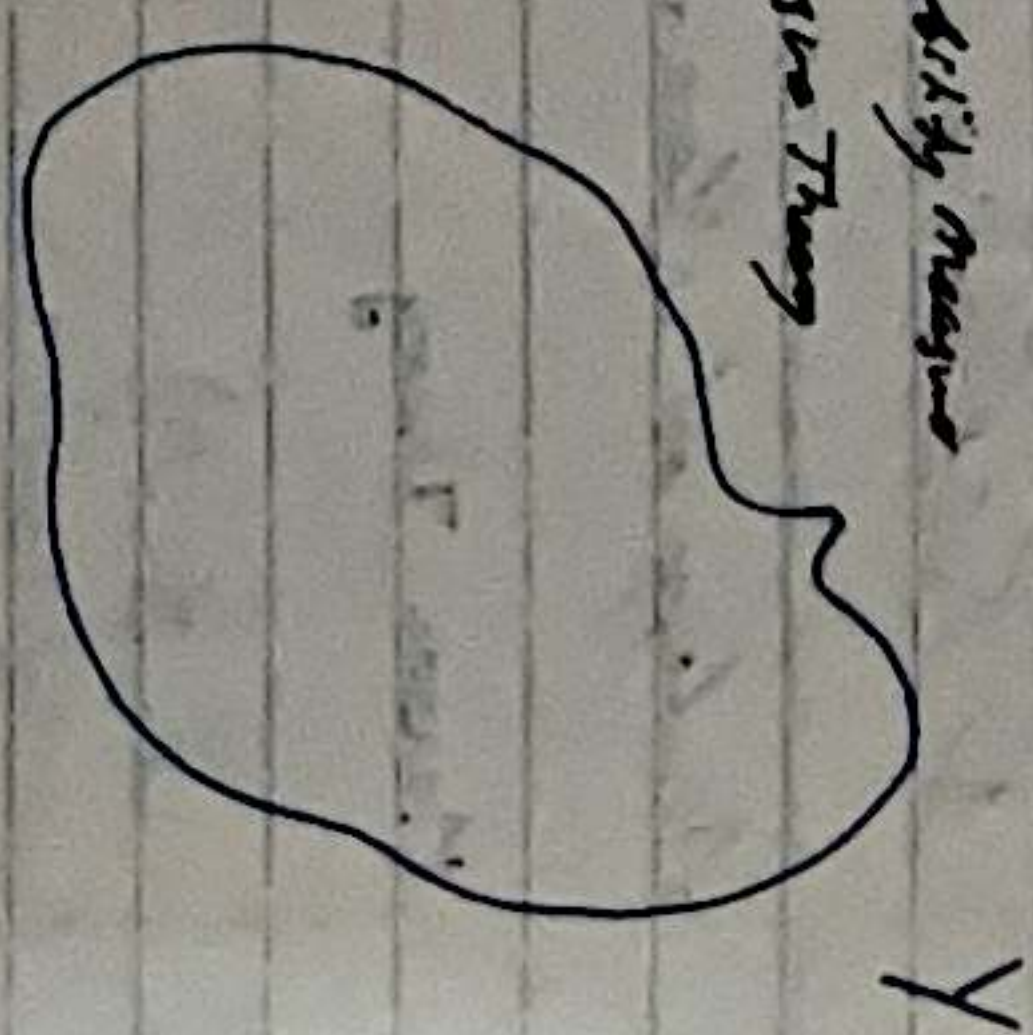
Have a list of info, how big each subset is

eg. 0.25, 0.10, 0.03, 0.02, 0.01

Expectation value

Statistical mechanics

Probability Measure Measure Theory



σ -algebra



Analogy of Measure Theory & Probability Theory.

Measure Theory

$$(X, \mathcal{B}, \mu)$$

X is the universe from which we are measuring.

e.g. $\mathbb{R} = \{\dots, 0, 1, \dots, 1.5, 2, 3, \dots\}$

~~$\mathcal{B} = \mathcal{B}(\mathbb{R})$~~

$\mathcal{B} = (\mathbb{R}, \mathcal{B})$

$\mathcal{B}$ is the σ -algebra

ensuring measuring occurs properly.

It contains subsets formed by the elements of $\mathbb{R}$.

It is seeded by $\mathbb{R}$

e.g. $\{\emptyset, \mathbb{R}, \{1\}, \{1\}^c\}$

$\hookrightarrow$ This is where the size of subsets are assessed.

$\mu: \mathcal{B} \rightarrow \mathbb{R}$

μ is a measure function

assessing the size of sets.

Probability

$$(\Omega, \mathcal{F}, IP)$$

$$IP(\Omega) = 1$$

Details about the σ -algebra.

In Probability, it defines the event.

Philosophy: Axioms $\rightarrow \emptyset$ & Ω included

$\hookrightarrow$ We define the largest and smallest elements when measuring

Suppose we get a rod.

We mark the

start & end.



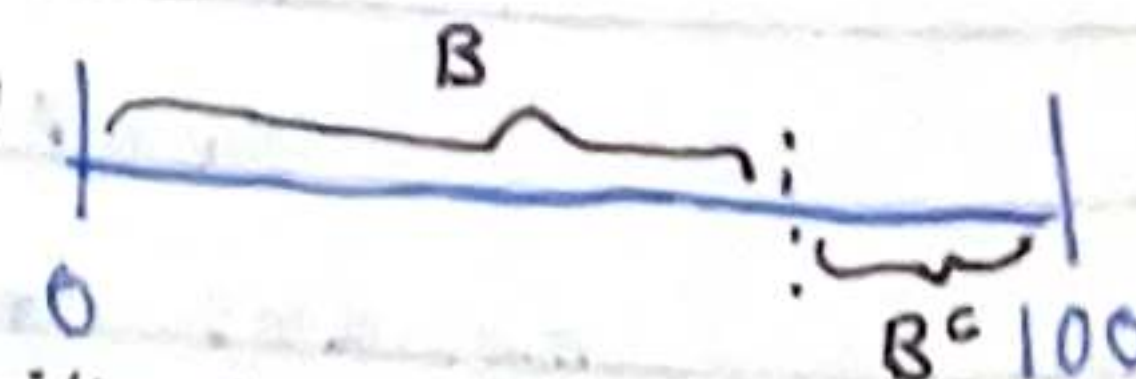
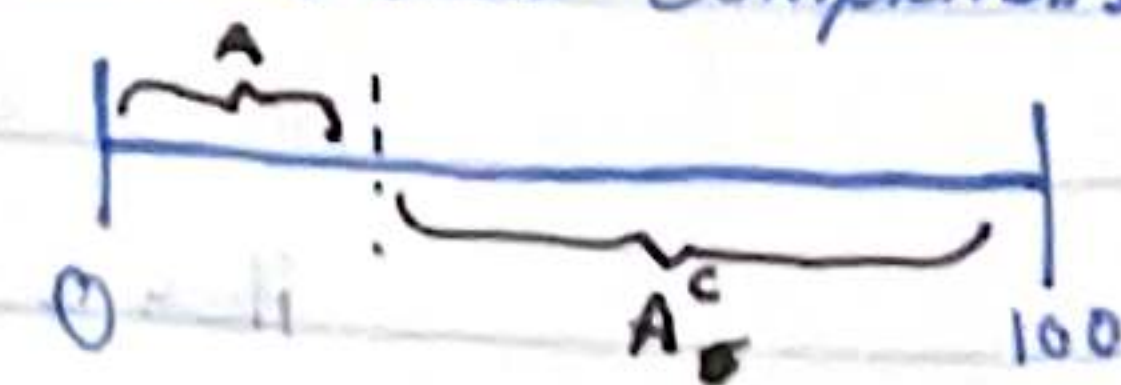
Closed under Complements.

However I divide it, there is always one part I choose, & another that

I reject (the complement)

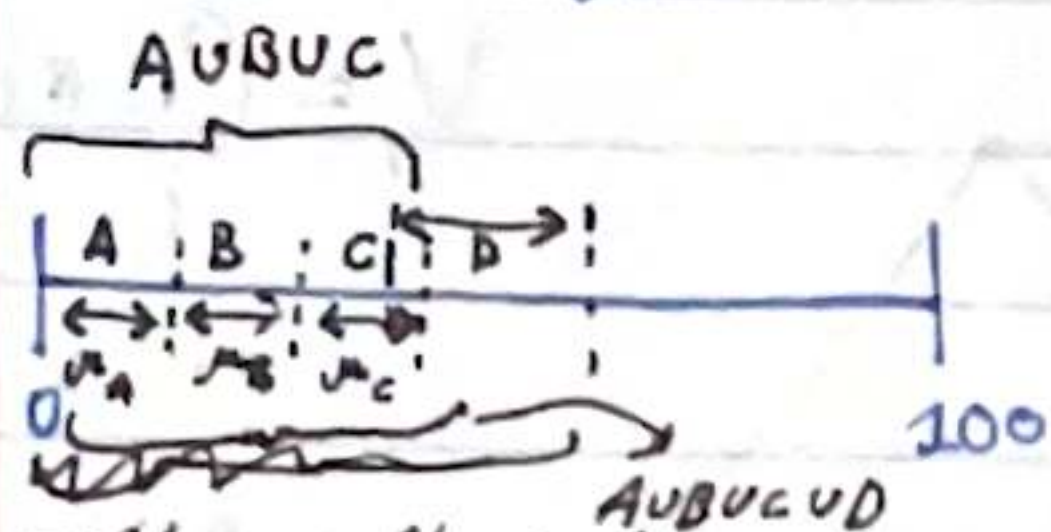
A division splits into

choosing & rejecting



* Dividing depends upon choosing A or B or C...

Closed under Union



It's not that deep I suppose.

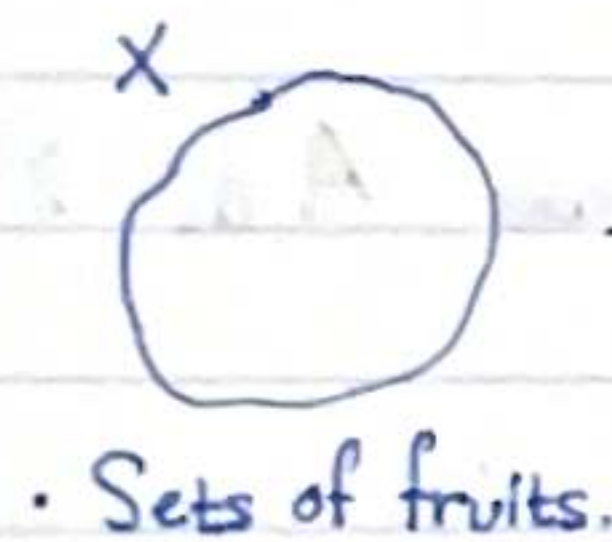
A bigger part can be made from smaller parts.

~~2/3~~

~~2/3~~

Measurable Functions

Size of Subsets (Splittings)



There are 10 red fruits
2 yellow fruits
1 green fruit
0 blue fruit
5 orange fruits

→ The random variable's definition is intricately tied to how the splitting is done (arbitrary)

If we segregate based on colour in σ, then let
Measurable function transfers the σ-algebra structure to this one

Information gets interpreted in terms of IR.

Probability mass distribution

$$f: X \rightarrow \mathbb{R}$$

$$f^{-1}(x) \in \sigma\text{-algebra}$$

• Dictates how the splitting is done.

[e.g. Segregate based on colour]
must take in account union and stuff like that (or use λ)

IR

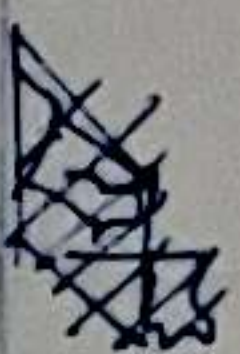


Borel σ-algebra



Bring it into being.

Collection of stuff



Philosophy

Phenomenology:

↳ Measurements

is inherently observer

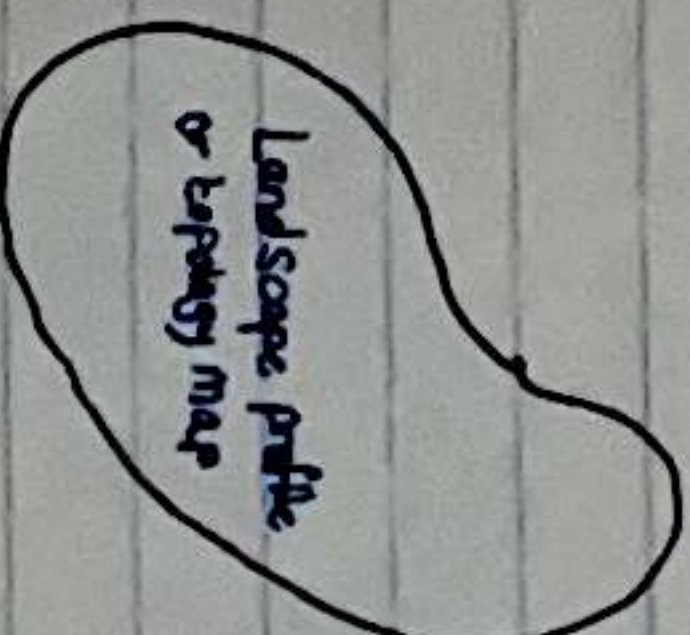
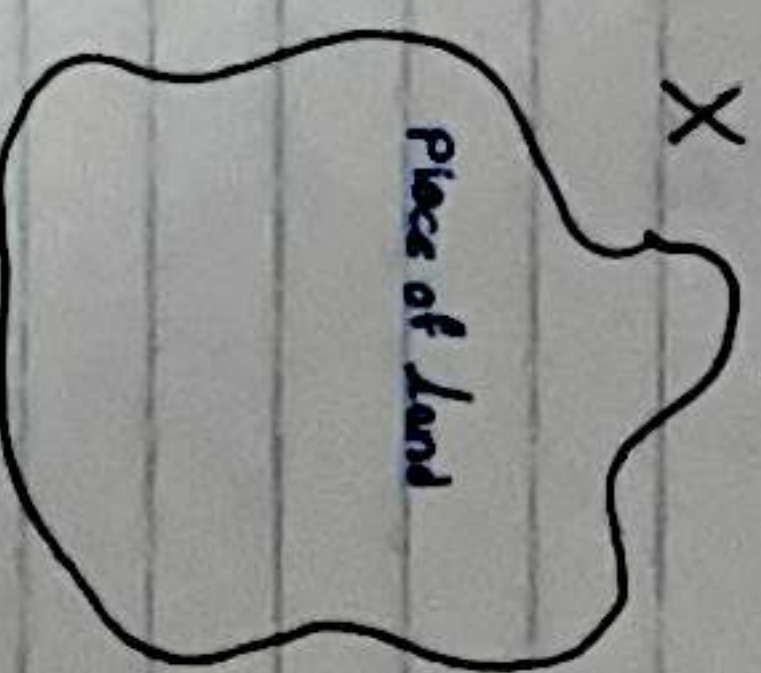
dependent. Measurement

is inseparable from

some

choice

Some Set X being a collection of stuff



$(X, \mathcal{T})$

$\mathcal{T}$ is a collection of

Subsets of X such that

Smooth "connections" between

data points is meaningful.

A topology on X provides the "Shape" and of the data being the "closeness" of points in the set.

Can you measure

something w/o choosing to measure it?

Implicitly

Choosing

the parts

we will

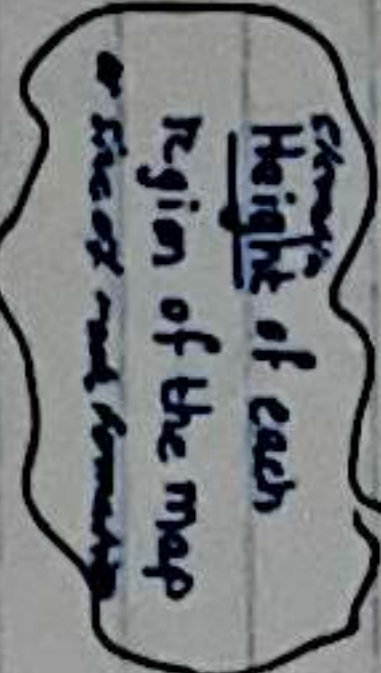
measure.

Partitioning land into parts which can be measured.

What do we want to measure is a good question.

Size of rocks
Height of land
Degrees of land

A σ -algebra (allows us to measure the "volume"/"importance" of each of these shapes on the set.)
Split the land in such a way that it can be measured.



(X, σ)
 σ -Algebra (measurable space)

This is done by the measure function μ .

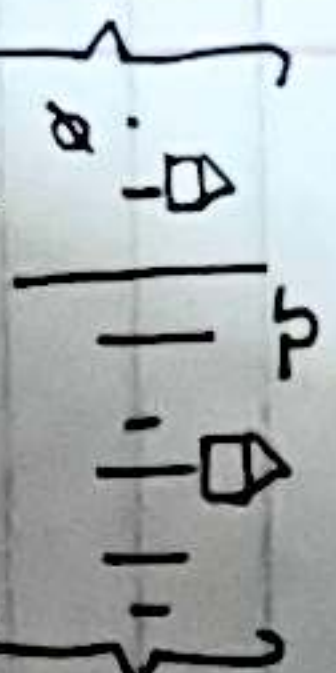
How to measure

↳ What even is measuring stuff?

Philosophy

Axioms: $\mathcal{A}$ & Ω included

Smallest & largest element included.



How do we interpret complement & union in terms of measure?

Land height

Height of villages above sea level: μ

+

Measure & Measurable Space = Measure Space
 μ (X, Σ) (X, Σ, μ)

$\mathcal{A}, \Omega$
Caratheodori min class
Complement class

Caratheodori additive

Elements of a measurable space are measurable

Why do the axioms make them measurable?

What can we measure?

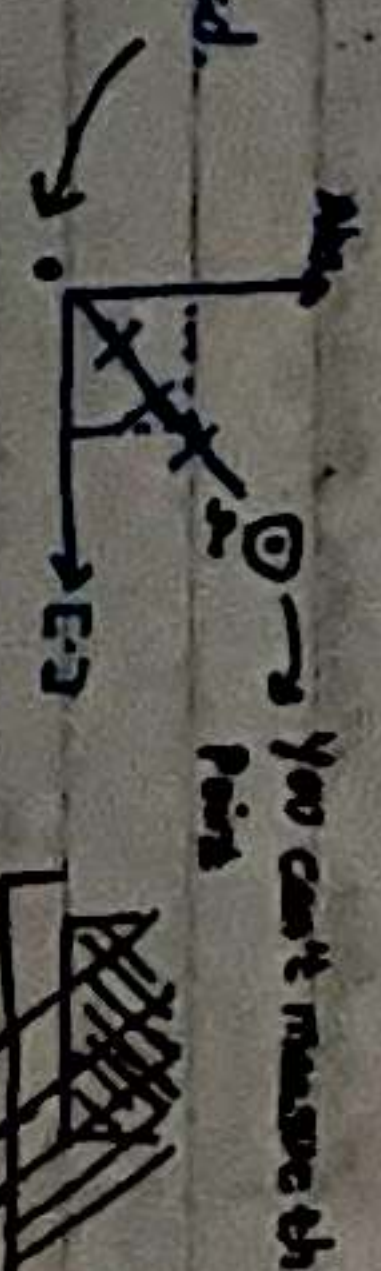
* A measurable space is a set equipped with a σ -algebra structure.

(X, Σ)
↳ Collection of subsets of X .

In our case, a subset would correspond to choosing a region of the landscape profile.

Axioms: There is an empty region ($\emptyset$) and the whole region (X or Ω) as part of the measurement structure.

① The measurement system is closed.



② Closed under complementarity.

↳ Why can we choose a subset A of landscape?

↳ Why can we implicitly state that it is not A^c (within a subset A)?

③ Closed under union

↳ Choosing from a landscape as a single choice of how many

land C

Measure Function

Optional !!

Piece of Land $\rightarrow$ Shape of Land
(or "closeness" of points)

(X, Σ)

Split landscape
into parts to
measure (X, Σ)

Measure
information
 (X, Σ, μ)

The contour
or topology

(Closeness) in terms
of what?

$\rightarrow$ Proximity

How similar
they are to each
other $\rightarrow$ related $\rightarrow$ How much they
belong to the same
open set...

If 2 points lie
within the many of
the same open sets,
they are considered close.

What we use

Lebesgue Classical probability :

$\frac{|A_i|}{|Q|}$ associated with region/measure/point !

Counting Measure $\mu(A) = \#$ of elements in A :

Dirac Measure : $\delta_a(A_i) = \chi_{A_i}(a)$

$\rightarrow$ indicator function

$= 1$ if $a \in A_i$
 $= 0$ if $a \notin A_i$

Borel Measure

$\rightarrow$ Gaussian Measure

Liouville Measure

$\rightarrow$ Liouville Theorem in classical
Mechanics

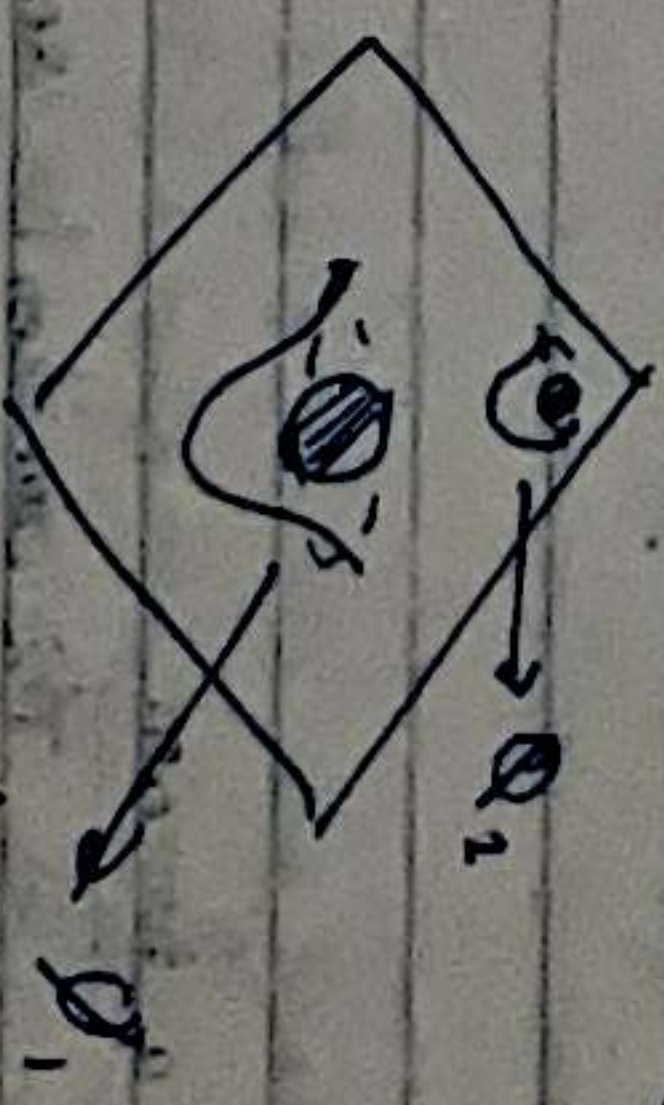
$\rightarrow$ Natural Volume form on a Symplectic manifold.

Gibbs Measure

$\rightarrow$ Canonical Ensemble

Physics

$\rightarrow$ Special distribution of Mass
 $\rightarrow$ Gravitational Potential



Make so much fucking sense !!!

Properties of Measure

① Monotonicity

If $E_1 \subseteq E_2$ then $\mu(E_1) \leq \mu(E_2)$

All the properties we previously said
in connection with probability.

Many of the laws of probability is simply
Measuring probability.

The question remains, what is probability?

Real Measurable function

$$f: X \rightarrow \mathbb{R}$$

So far, μ gave us the following:

Subsets (egs)	Size of a measured property
...	...

Intuitively, the measurable function f maps the price of land to $\mathbb{R}$ while carrying measured properties are preserved.

Why should we want to do that?

If also transfers the measure μ to $(\mathbb{R}, \mathcal{B}(\mathbb{R}))$ and the new push forward measure is denoted $f_{\#}\mu$.

It turns the measure into a function.

This can then be used for further analysis

* It forms a function from the table we obtained.

That function can then be used for mathematical analysis.

$\mathbb{R}$ (Real Analysis)

f maps $(X, \Sigma) \rightarrow (\mathbb{R}, \mathcal{B}(\mathbb{R}))$

$\mathbb{C}$ (Complex Analysis)

$$\forall B \in \mathcal{B}(\mathbb{R}) \quad f^{-1}(B) \in \Sigma$$

$$\int_X f d\mu \text{ is well defined}$$

e.g. ~~Gaussian Distribution & Gaussian Measure~~

We always integrate

Integration, Measures and Measurable functions

Measurable functions w.r.t. a measure.

Lebesgue Integration w.r.t. measure μ

$f: X \rightarrow \mathbb{R}$ is a measurable function

X is the domain of integration

μ is measure defined on measurable space $(X, \mathcal{B})$

$d\mu$ indicates integration performed w.r.t. μ

$$\int_X f d\mu$$

For every subset A in X , f converts that (value) into a $\mathbb{R}$ quantity (while accounting for weighting based on μ).

μ determines how the size of the subsets of X contributes to the integral.

$f: X \rightarrow \mathbb{R} \quad f: a \mapsto x$ where $a \in X$ and $x \in \mathbb{R}$.

$\mu = \lambda(x)$ Lebesgue Measure

$$\text{Lebesgue Integral} = \int f(x) d\lambda(x)$$

first a measurable function from X .

We are integrating over the domain X . f is a

The range of $f: X \rightarrow \mathbb{R}$ is $f(x) \in \mathbb{R}$

We then weigh the range based on the size of the domain using the measure λ .

λ is a

Lebesgue's theory define integration for a class of functions called

Measurable functions.

(X, Σ, μ) $f: X \rightarrow \mathbb{R}$

A function f on X is measurable

if the preimage of every interval of the form (t, ∞) is in Σ

$\{x | f(x) > t\} \in \Sigma \quad \forall t \in \mathbb{R}$

Measure $\rightarrow f(x)$ is same as $X \rightarrow r.v$
 theory

Let $r.v$ X be sum of d dice
 $X = d_1 + d_2$
 $f: d_1 + d_2 \mapsto x \in \mathbb{R}$
 $f(x) = d_1 + d_2$

Probability

$(\Omega, \mathcal{F}, \mathbb{P})$

It makes sense that if we have a topological landscape and we measured an average quantity for each region, and we converted that variation in quantity to a function.

The "average" value of that function could correspond to the average value of that quantity over the topological landscape.

In probability space, the measure $\mathbb{P}$ could give the probability associated with each region e.g. $\mathbb{P}(A_i) = \frac{|A_i|}{|\Omega|}$

The function X which interprets a subset as a value on $\mathbb{R}$ is the representation of that subset. X is called a random variable.

We then weigh the (interpretations of the subsets) with the probability measures $\mathbb{P}(A_i)$

This gives the average value of the interpretation of the subsets.

This corresponds to the expected value $\mathbb{E}$

$$\mathbb{E}[X] = \int_{\Omega} X d\mathbb{P}$$

$\int_{\mathbb{R}} x dX_{\# \mathbb{P}}$
 x is the subset converted to in $\mathbb{R}$ too, not only $\mathbb{P}$

$$\mathbb{E}[X] = \int_{\Omega} X d\mathbb{P}$$

$\rightarrow$ The expectation of X .

$\rightarrow$ random variable.

Note X must be

It must match

properly defined...

The σ -algebra $\leftarrow$ Can't define random variables in any stupid ways we want

Push forward Measure & Integrability on $\mathbb{R}$

Variance in Probability Space & its equivalence in Measure Spaces.

$\hookrightarrow$ Just L^2 -norm of $(\mathbb{E}[X] - X)$.

To summarize real measurable functions & Lebesgue integration.

Why do we even define a measurable function and what are its properties.

It allows for mathematical analysis of sets and sets with functions instead of a point (subset, quantity)

the pairs are generated by a measure. The measurable function turns these into a rule/function.

It allows for generalization of

Generality & Gaussian Random Variable

$$\mathbb{E}[X] = \int_{\Omega} X d\mathbb{P}$$

$$= \int_{\mathbb{R}} x dX_{\# \mathbb{P}}(x)$$

$\rightarrow$ living in $\mathbb{R}$ only.

that is the point

Integrating over $\mathbb{R}$

the subsets in the

measure space

w.r.t the measure

$\mathbb{P}$.

Integrating over $\mathbb{R}$

w.r.t the pushforward

measure $X_{\# \mathbb{P}}$ induced

by measurable function X .

$\hookrightarrow$ The pre-image $X_{\# \mathbb{P}}^{-1}(x)$ of the induced measure $X_{\# \mathbb{P}}$ must lie inside in the Borel σ -algebra $\mathcal{B}(\mathbb{R})$.

The pre-image $X_{\# \mathbb{P}}^{-1}(A_i)$ of the measurable function X must be a subset present in the σ -algebra $\mathcal{F}$.

The σ -algebra $\mathcal{F}$.

Boolean Algebras & Sigma Algebras

Σ -Algebras

Set of subsets of X

A σ -algebra over a set X is a subset $\Sigma \subseteq \mathcal{P}(X)$ satisfying:

- 1) For i countable, $U_i \in \Sigma \Rightarrow \bigcup_{i=1}^{\infty} U_i \in \Sigma$ (countable) $\left\{ \begin{array}{l} I \text{ countable set } (0 \leq |I| < \infty) \\ i \in I \end{array} \right.$
- 2) $U \in \Sigma \Rightarrow X \setminus U \in \Sigma$

A measurable space is a pair (X, Σ) where X is some set and Σ is a σ -algebra over X .
In such situations, a subset $S \subseteq X$ is called measurable iff $S \in \Sigma$

Note: It follows from 2 that $\emptyset \in \Sigma$, $X \in \Sigma$
Also, Σ is closed under countable intersection.

Fix a measurable space (X, Σ) . A measure on (X, Σ) is a function $\mu: \Sigma \rightarrow [0, \infty]$ s.t

$$\mu(\emptyset) = 0$$

- 1) $i \in I$ countable, $U_i \in \Sigma$

$$U_i \cap U_j = \emptyset \text{ for } i \neq j$$

Disjoint Sets

$$\mu\left(\bigcup_{i \in I} U_i\right) = \sum_{i \in I} \mu(U_i)$$

A measure space is a triple (X, Σ, μ) where (X, Σ) is a measurable space and μ is a measure on (X, Σ)

USRA

Asa Bue & Gher
Teachers for paid 2019.

Arithm

Equivalence class case decomposition.

Boolean Algebras

Review of Order Theory $\rightarrow$ previously reviewed in Binary relations

Posets

A poset is a set equipped with a partial order.

$(P, \leq)$

A set P is a binary relation on P satisfying

partial order properties.

A binary relation satisfying certain properties

$\hookrightarrow$ A binary relation on set P is a rule or condition determining whether two elements

of P are related. It is a subset of $P \times P$.

e.g. relation $\in$; $A \in B$ can be true or false.

It is a relation that is either true or false giving

or is it called binary because 2 elements are

involved? $\hookrightarrow$ It is called binary because

2 elements involved.

The true/false value is a property of all relations.

Relations are

fundamental mathematical

relationships $\hookrightarrow$ equivalence relations??

is divisible by,...

Binary Relations may have some or none of the following properties.

- 1) Reflexive, $\forall a \in P, a \leq a$
- 2) Symmetric, $a \leq b \Rightarrow b \leq a$
- 3) Antisymmetric, if $a \leq b$ and $b \leq a$ then $a = b$
- 4) Transitive, if $a \leq b$ and $b \leq c$ then $a \leq c$

$\hookrightarrow$ These can represent any relation

is greater than, is a friend of, is better than,

is divisible by,...

Partial order, $\leq$ is a special type of binary relation satisfying the properties of: Reflexive, Antisymmetric and Transitive.

Symmetric not necessary

any element

No two distinct

is related to

itself

consistently across elements.

in same way.

For Set P , $(P, \leq)$

Meaningful relation.

- Elements are members of the set P
- Two elements $a, b \in P$ are comparable if either $a \leq b$ or $b \leq a$. is a poset where all elements
- Two elements $a, b \in P$ are incomparable if neither $a \leq b$ nor $b \leq a$ of P are comparable.

• A partial order allows for

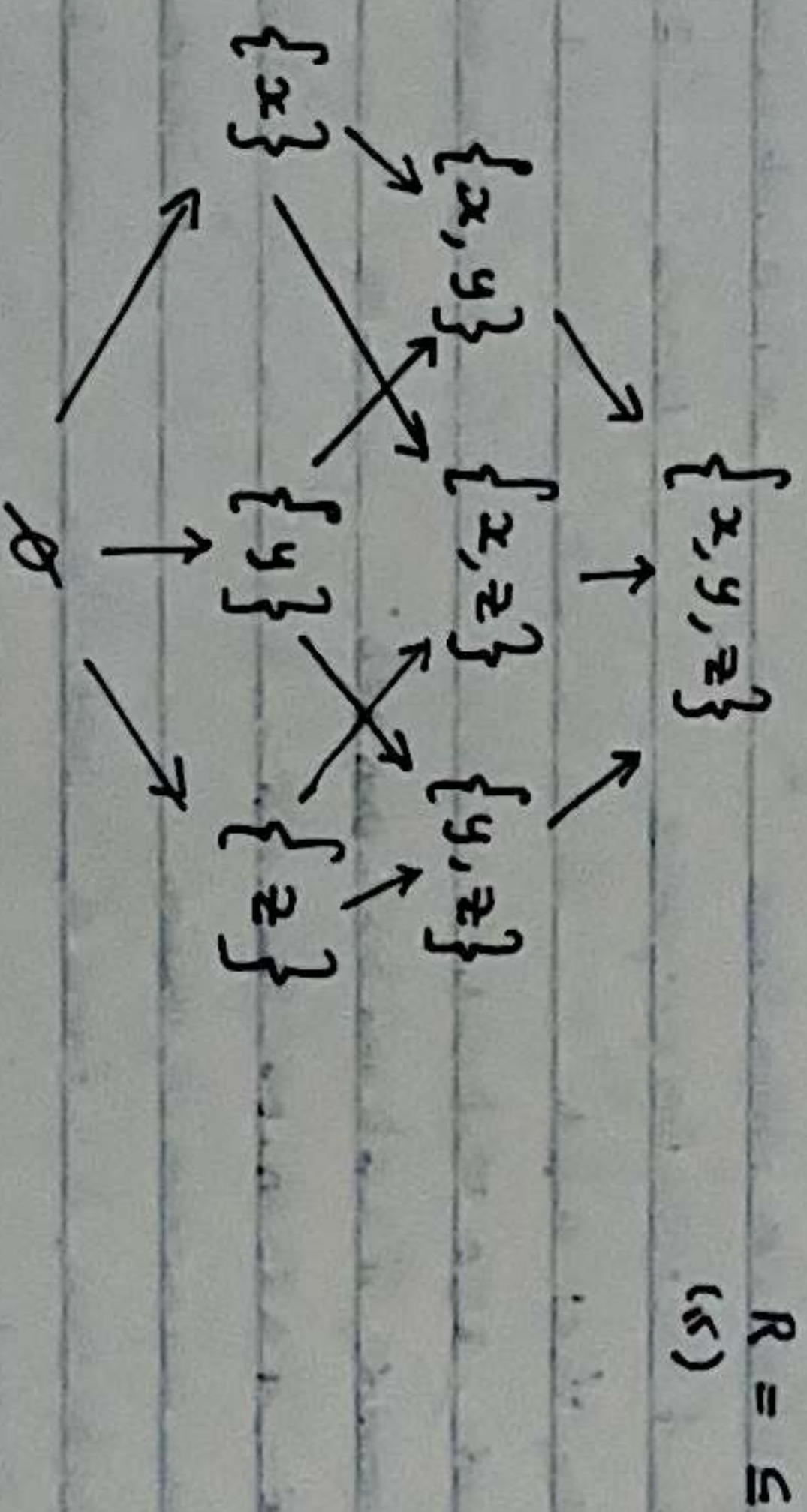
Examples of Posets

$(P, \leq)$ where $P = \mathcal{P}(\{x, y, z\})$ and $\leq$ is $\subseteq$

Subset relation. Incomparable elements.

Easy to show that $\subseteq$ is reflexive, Antisymmetric and Transitive.

$$① P = \{\emptyset, \{x\}, \{y\}, \{z\}, \{x, y\}, \{x, z\}, \{y, z\}, \{x, y, z\}\}$$



$$R = \subseteq$$

$$② P = \{1, 2, 4, 8, 16\}$$

$\leq$ = "divides"

$$③ P = \mathbb{R}$$

$\leq$ = usual "less than"

Key Elements in a poset.

• Minimal Element

least

When we say minimum/maximum, we mean in terms of order and not "size".

Warning

• Maximal Element

• Least Element

• Greatest Element

• Least Upper Bound/Suprema

• Greatest Lower Bound/Infima

• Suppose we have a poset P and S is a subset of the poset P . $x \in S$ minimal s.t. $\forall y \in S, y \leq x$.

There is no element which x is "less than" or there is no element which x is "greater than". This is not the same as least element.

There can be multiple minimal elements in a set & the minimal is not necessarily the least.

Trying dotnet signal

$\hookrightarrow$ Resonance frequency - Reactance $X_L = \text{Reactance}_C$

$I \rightarrow \infty$

Maximum possible

oscillation.

Fifth Parallel L-C Circuit

What to reject $\rightarrow$ Can suppress $\hookrightarrow$ Fear of death $\hookrightarrow$ Can't stop growth

Dual

Do category of posets

Admit co-posets

like poset less than

form poset greater than?

Maximal Element

[Maximal]
 $x \in S$ is maximal in a subset S of Poset P if there is no element $y \in S$ s.t.
 $x < y$.

$\nexists y \in S$ s.t. $x < y \Rightarrow x$ is maximal.

Minimal & Maximal Elements that have no "smaller" or "larger" elements within a subset, but they don't need to be comparable with all other elements.

e.g. Under $\leq$ for $S = \{2, 3\}$

Minimal = 2 } In this case, they also
 Maximal = 3 } correspond to least and greatest.

e.g. $\{2, 3\}$ under divisibility

Minimal elements: 2 & 3 (neither is divisible by the other)

Maximal elements: 2 & 3 (neither divides the other)

Least and Greatest Elements refer to absolutely the smallest or largest element in a subset S of a poset P . They are comparable to all elements in S and they are unique if they exist.

Least Element, $x \in S$ is least element of S if $x \leq y \forall y \in S$

Greatest Element, $x \in S$ is the greatest element of S if $y \leq x \forall y \in S$.

e.g. $\{1, 2, 3\}$ under $\leq$

Least: 1

Greatest: 3

$\{2, 3, 5, 6\}$ under divisibility

Least: 2 (divides all other elements)

Greatest: No Greatest Element.

No single number is divisible by all other.

Supremum & Infimum

Sup $\downarrow$ inf

These describe bounds relative to the whole poset, not just the subset.

We say the Sup of a subset, not the

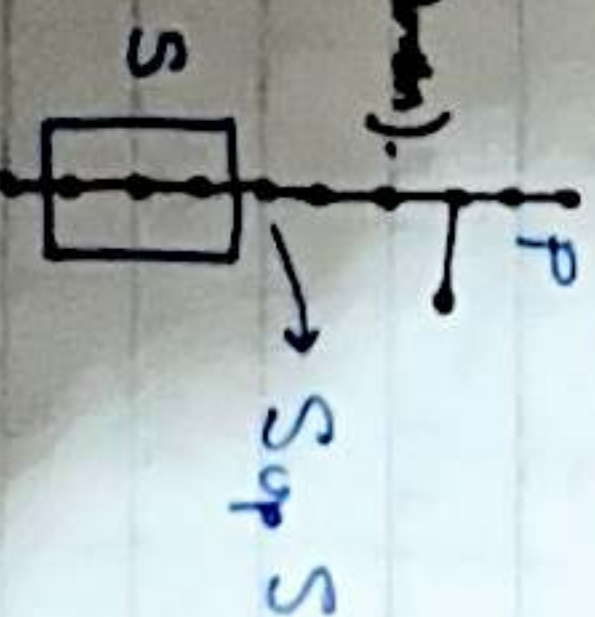
Supremum (Join, Least Upper Bound)

The Supremum of a subset $S \subseteq P$ is the smallest element in P that is greater than or equal to all elements of S .

$\nexists$ The Supremum is global to P (the whole poset in context).
 It acts as a bound to Subset S .

Conditions: Greater or equal to all of S

AND the smallest element in P
 that satisfies the above condition



$\rightarrow$ if Sup is in S , it is the greatest element
 not in $S \rightarrow$ Acts as a bound
 it may or may not exist if poset lacks
 sufficient elements

Infimum (Meet, Greatest Lower Bound)

The infimum of a subset $S \subseteq P$ in a poset P is the largest element in P that is less than or equal to all elements in S .

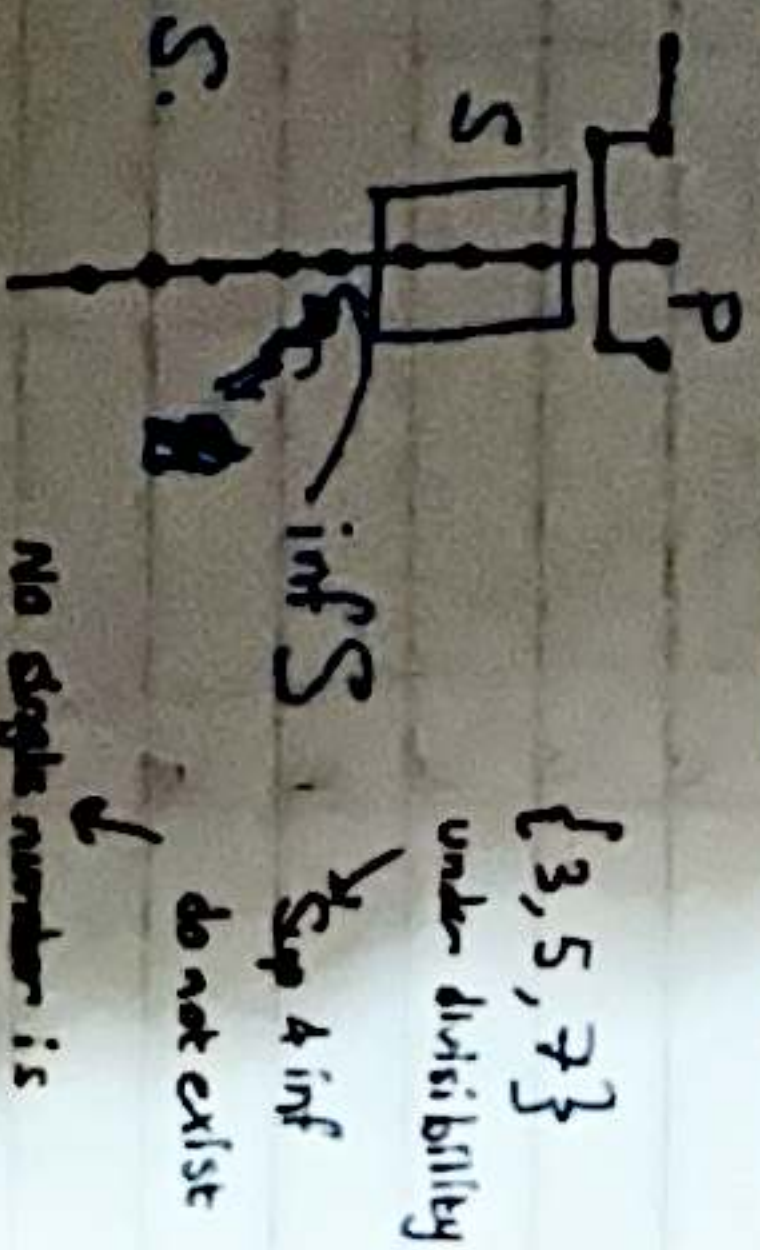
Inf $S \in S \Rightarrow$ least element

Inf $S \notin S \Rightarrow$ Bound

e.g. $[0, 1] \subseteq \mathbb{R}$ under $\leq$ Largest in P

Sup = 1 That is less than S .

inf = 0



$\{3, 5, 7\}$

under divisibility.

Sup & inf

do not exist

No single number is
 divisible or divides all 3.

Probability

- The sample space Ω is the set of all possible outcomes.

e.g. $\Omega = \{H, T\}, \{1, 2, 3, 4, 5, 6\}, \{R, B, G, Y, O, P\}$

↘ Single coin flip

↘ Single die toss

- * An event specifies the outcome we are interested in. It is a subset of the sample space.

e.g. $\{4\}$ rolling 4

$\{2, 4, 6\}$ rolling an even number

The elements of the event space

all satisfy the event specified and none other.

- A σ -algebra ($\mathcal{F}$) is a collection of subsets of the sample space Ω that satisfy the following properties.

$\Omega \in \mathcal{F}$

$\emptyset \in \mathcal{F}$

if $A \in \mathcal{F}$ then $\Omega \setminus A \in \mathcal{F}$

if $A_1, A_2, A_3, \dots \in \mathcal{F}$ then $\bigcup_{i=1}^{\infty} A_i \in \mathcal{F}$

These axioms allow for a measure space $(\Omega, \mathcal{F}, \mu)$ to be defined. Those subsets which are measurable can be in the σ -algebra and can be assigned probabilities

- * An event is a subset that:
1) Satisfy the event specified
2) belong to $\mathcal{F}$

This ensures that probability can be defined for these events.

→ Events are elements of the σ -Algebra and the latter determines which subset of Ω are valid events.

- A probability space $(\Omega, \mathcal{F}, P)$ is a measure that ensures all elements of $\mathcal{F}$ sum up to 1.

It obeys the axioms of the σ -algebra as well as the following:

$P(\emptyset) = 0$

$P(\Omega) = 1$

$P(A) \geq 0$

$P\left(\bigcup_{i=1}^{\infty} A_i\right) = \sum_{i=1}^{\infty} P(A_i)$

These ensure that probability is calculated as traditionally done.

~~You don't need to think to live.
You don't need to be smart to live.
You don't need to solve problems to live.
Don't think too much.~~

① $\emptyset, \Omega$

② Closed under Complementarity

③ Closed under (finite) Union

~~σ~~-algebra

axioms

↳ This is very fucking arbitrary, It depends on how we define the measure

↳ Leplac Measure

↳ Dirac Measure

↳ Lebesgue measure

For intuition of measure, need more details into σ-algebras

Like selecting the height of a rock, we select an event...

More details into σ -algebras

σ -algebras are a collection of subsets of Set X
or σ -algebras are each subsets of the power set of X .

Defn: $\mathcal{A} \subseteq P(X)$ s.t. $\emptyset, X \in \mathcal{A}$
if $A \in \mathcal{A}$ then $X \setminus A \in \mathcal{A}$
if $A_i \in \mathcal{A}, i \in \mathbb{N}$ then $\bigcup_{i=1}^{\infty} A_i \in \mathcal{A}$

then $\mathcal{A}$ is called a σ -algebra.

$A \in \mathcal{A}$ is then a measurable set

Sigma algebra



We want to find the smallest $\mathcal{A}$ on X given we have a lot of $\mathcal{A}$'s on X .

$\bigcap_{i \in \text{Index}} \mathcal{A}_i$ is also a σ -algebra $\rightarrow$ Intersection of 2 σ -algebras will give a new smaller one.

Can keep this going for however many indices we want
and we will keep getting smaller & smaller.

Suppose we are interested in a particular group of outcomes in a sample space (a family of subsets in the power set of X), $\mathcal{M}$.

e.g. $\{\{1, 2\}, \{3, 4\}, \{5, 6\}\}$ or $\{\{1, 2, 3\}, \{4, 5, 6\}\}$

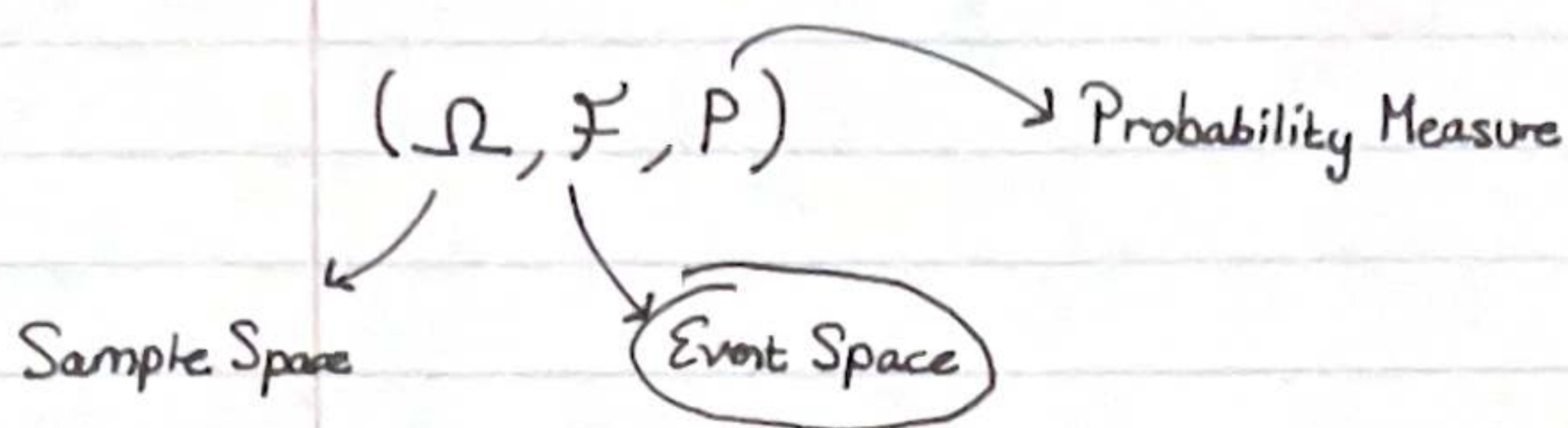
For that $\mathcal{M} \subseteq P(X)$, there is a smallest σ -algebra that contains that subset $\mathcal{M}$.

As we saw earlier, intersection yields a smaller σ -algebra,

$\bigcap_{\mathcal{A} \in \mathcal{K}} \mathcal{A} \rightarrow$

$\mathcal{A}$ is a σ -algebra.

More details into σ -algebras



Let $\Omega \neq \emptyset$ be a set. Let $\mathcal{P}(\Omega)$ be its power set.

Then $\mathcal{F} \subseteq \mathcal{P}(\Omega)$ is a σ -algebra if it satisfies

- $\Omega \in \mathcal{F}$
- $\emptyset \in \mathcal{F}$
- $A \in \mathcal{F} \Rightarrow \Omega \setminus A \in \mathcal{F}$
- $A_1, A_2, A_3 \in \mathcal{F} \Rightarrow \bigcup_{i=1}^{\infty} A_i \in \mathcal{F}$ (closed under countable unions)

Note: $\mathcal{F}$ is also closed under countable intersection

Proof

$$\bigcup_{i=1}^{\infty} A_i \in \mathcal{F}$$

$$\text{Since } A \in \mathcal{F} \Rightarrow \Omega \setminus A \in \mathcal{F}$$

$$\Rightarrow \bigcup_{i=1}^{\infty} A_i^c \in \mathcal{F}$$

Again this union is also a set in $\mathcal{F}$; and so is its complement

$$\bigcup_{i=1}^{\infty} A_i^c \in \mathcal{F} \Rightarrow \left(\bigcup_{i=1}^{\infty} A_i^c \right)^c \in \mathcal{F} \xrightarrow[\text{De Morgan's Laws}]{} \bigcap_{i=1}^{\infty} A_i \in \mathcal{F}$$

Examples of σ -algebras

~~Let $\Omega \neq \emptyset$~~

~~1) $\mathcal{F}$~~

(a)

1) $\{\emptyset, \Omega\} \rightarrow$ Trivial σ -algebra

2) $\{P(\Omega)\} \rightarrow$ discrete σ -algebra

3) Let $A \subseteq \Omega$ then $\{\emptyset, A, A^c, \Omega\}$ is a σ -algebra

$$\emptyset^c = \Omega, \Omega^c = \emptyset$$

$$(A)^c = A^c, (A^c)^c = A$$

$$A \cup A^c = \Omega$$

$$\emptyset \cup A = A$$

$$\emptyset \cup A^c = A^c$$

and so on...

σ -Algebras generated by a set

Let $T \subseteq P(\Omega)$

Then, there exist a unique smallest σ -algebra which contains every set in T .

↳ This is called the σ -algebra generated by T ($\sigma(T)$)

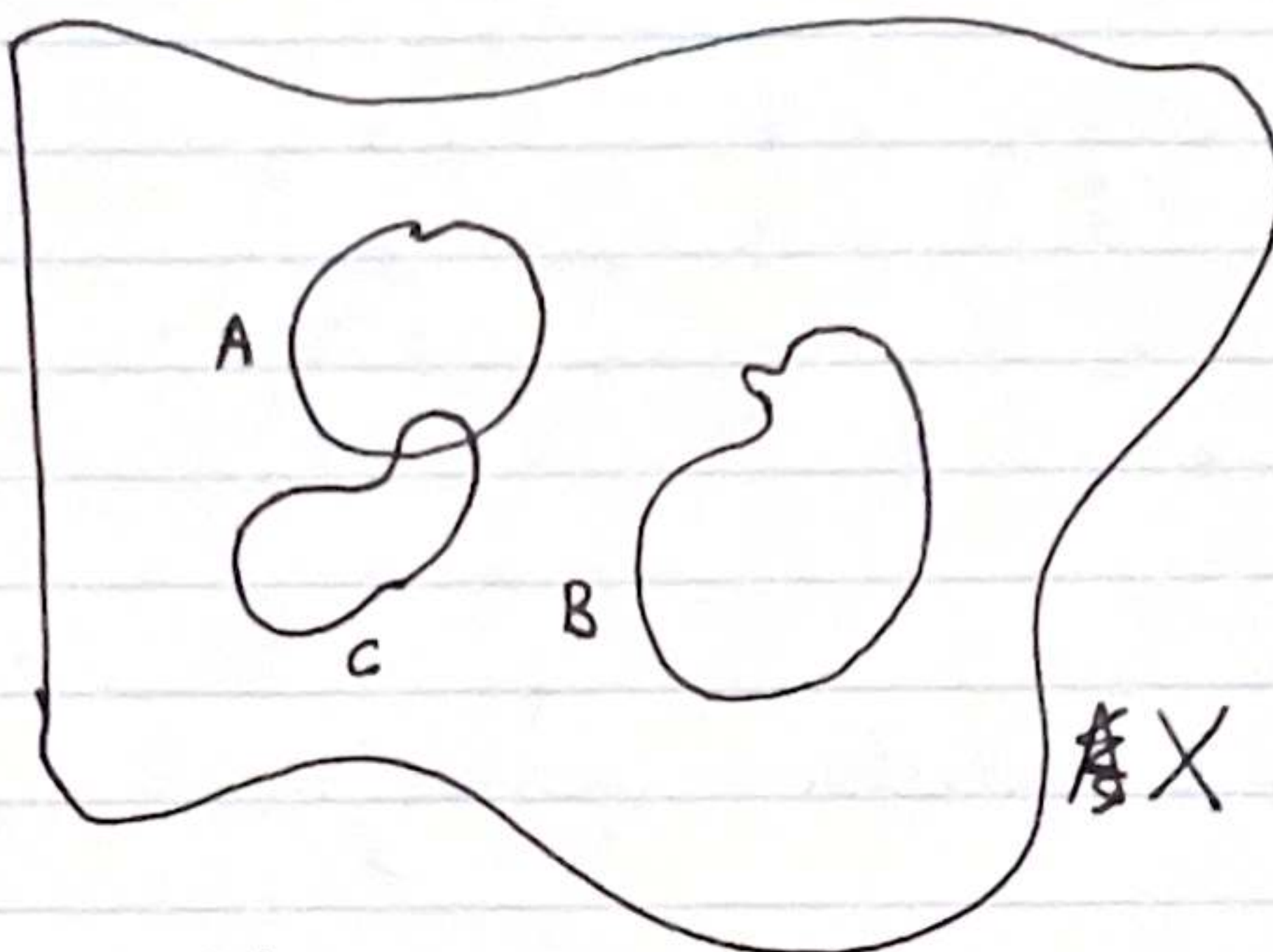
$$\sigma(T) = \left\{ \text{Countable union \& intersections of the complement of the elements of } T \right\}$$

↳ Subsets

Topology.

I think I covered metric space defn and some elementary point-set defn before. I also covered them for Measure Theory I think.

We have Sets



These are elements grouped by

membership, forming a Set. It can be anything from the Set of animals to the Set of real numbers.

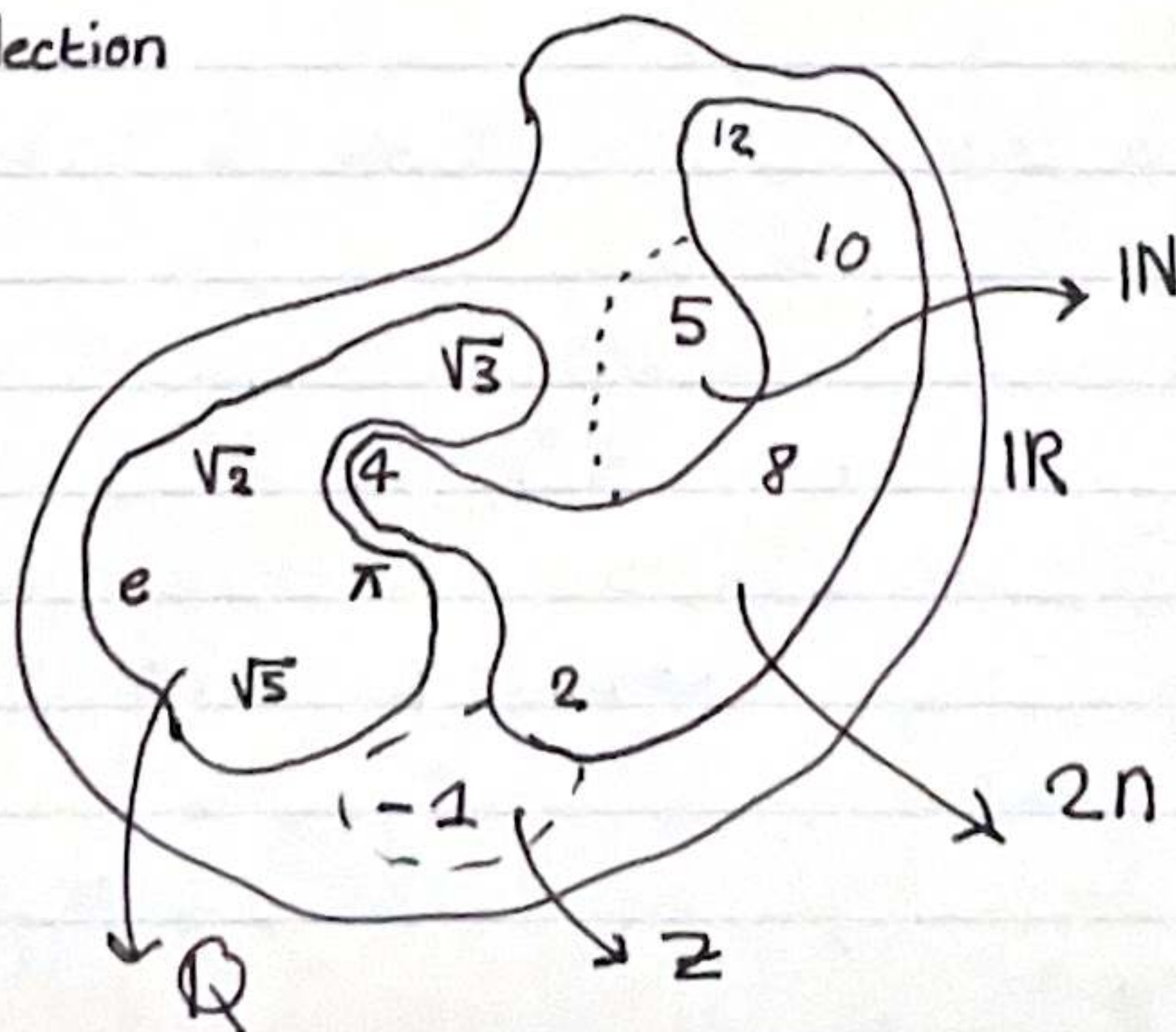
New Sets can be formed by union, intersection, Set difference, Complement.

Order Theory: $a < b$, $a, b \in X$ (You can impose structure and add order to a Set, by classifying its elements according to a relation).

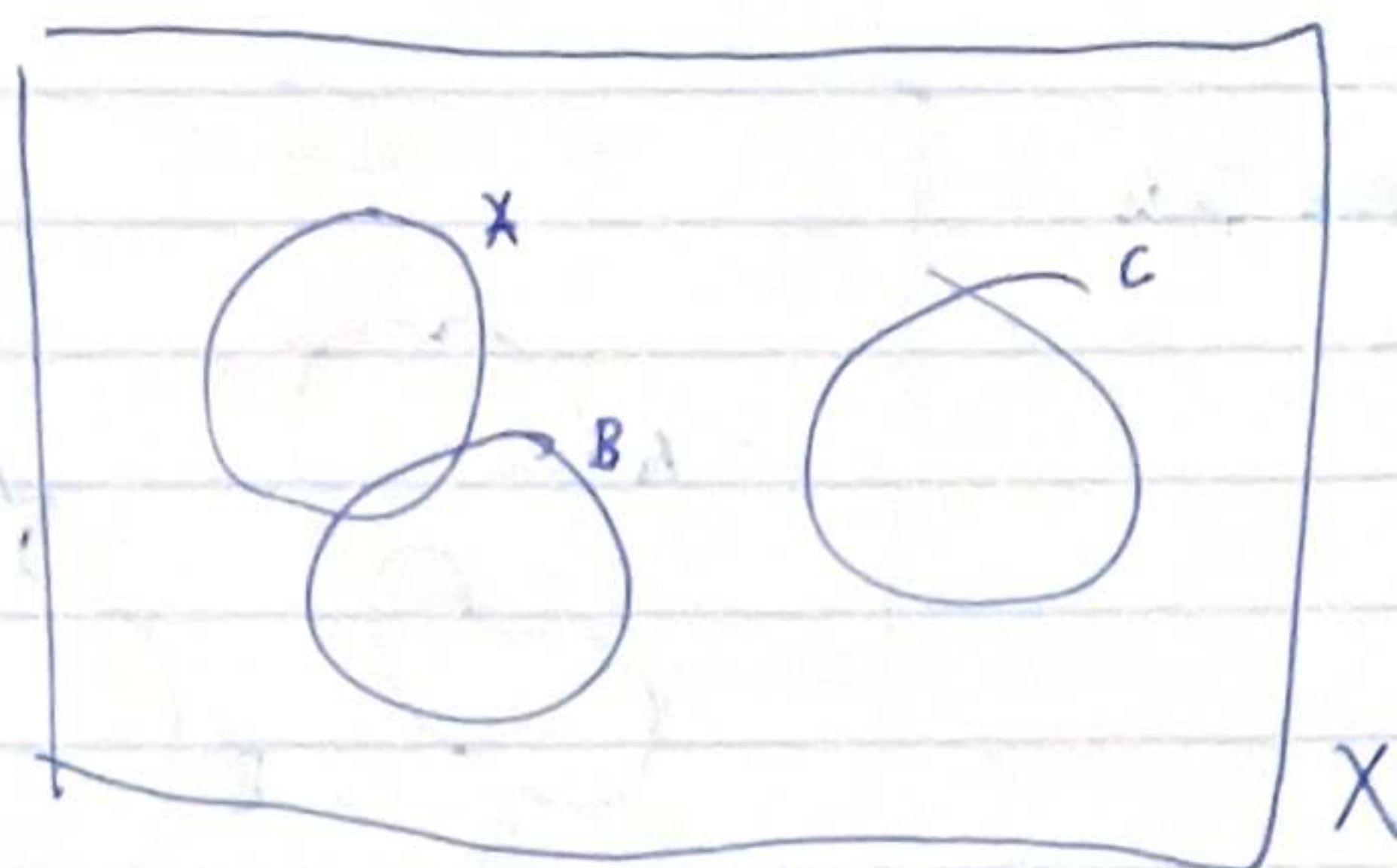
These are just collections of objects.

You can have the set of $\mathbb{Q}$ in $\mathbb{R}$ or the set of even numbers.

It is just a collection

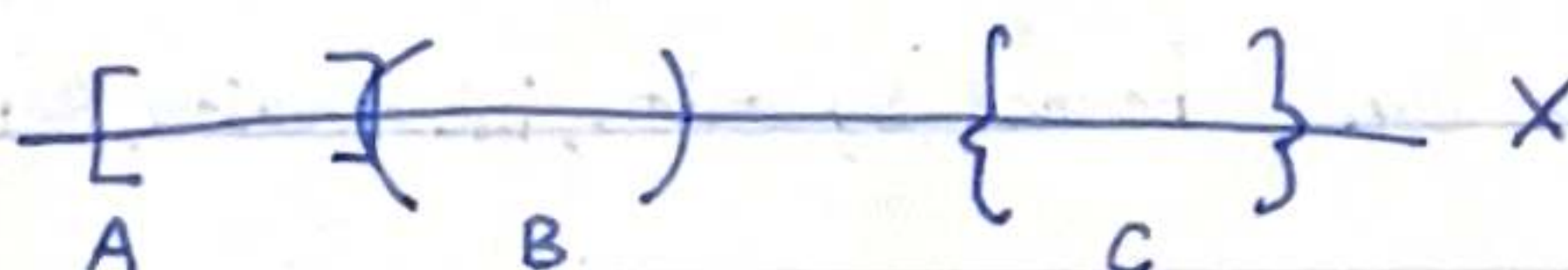


Consider a set of subsets.



(X is a collection of subsets)

A has all elements with a common property, so do B & C.



There can be union & intersection and all other elementary set operations.
~~Sets like these define a "closed" collection of elements~~

That's the most basic way of viewing objects. Categorization into elements sharing a common property.

What about another way of viewing the collection?

Motivation: I have intersection which can measure the overlapping of points.

The Union sum of that intersection could interpret proximity in a meaningful way?

This contributes to the concept of nearness for each subset.

$$\bigcup_{x \in X} \text{Points}_x$$

$\mathcal{T} \subseteq \mathcal{P}(X)$ is a topology on X if:

$\emptyset, X \in \mathcal{T}$

$\bigcup_{\alpha \in A} U_{\alpha} \in \mathcal{T}$ for any subcollection (arbitrary union)

$\bigcap_{i=1}^n U_i \in \mathcal{T}$ for any finite subcollection.

Topology
Axioms
required

for the algebra of
open sets:

$\emptyset$ & X form part of $\mathcal{T}$ are
and are defined as open.

Arbitrary unions of open sets are open
If we can cover a space using
open parts, then the whole covered space
is open too

Why arbitrary

Union index
can be
finite, infinite, uncountable

Allow cover
for infinite
space line
 $\mathbb{R}$ with union
of small open sets
to make the
whole thing
open.

Finite intersection requirement.

Consider $A_n = (-\frac{1}{n}, \frac{1}{n})$

$$\bigcap_{n=1}^{\infty} A_n = \bigcap_{n=1}^{\infty} (-\frac{1}{n}, \frac{1}{n})$$

$$A_1 = (-1, 1)$$

$$A_2 = (-\frac{1}{2}, \frac{1}{2})$$

$$A_3 = (-\frac{1}{3}, \frac{1}{3})$$

$$\dots A_3 \subset A_2 \subset A_1$$

Each subsequent set is contained in the other.

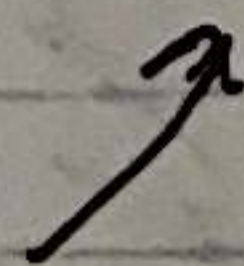
$$\vdots A_3 \cap A_2 \cap A_1 = (-\frac{1}{3}, \frac{1}{3})$$

$\vdots$

If keeps going to the smallest finite case k

$$\Rightarrow \bigcap_{n=1}^k (-\frac{1}{n}, \frac{1}{n}) = (-\frac{1}{k}, \frac{1}{k})$$

Smallest overlap



$$\lim_{n \rightarrow \infty} A_n = \lim_{n \rightarrow \infty} \left\{ A_n \right\}_{n=1}^{\infty}$$

An infinite union is the limit of a sequence of finite union

→ We can't take limit of a Set; $(-\frac{1}{k}, \frac{1}{k})$ is a set.